Abstracting Program Dependencies Using The Method Dependence Graph

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Dependence analysis underlies many tasks

Motivation



Traditional dependence model is heavyweight

Motivation

Offer fine-grained results

Suffer from low scalability

```
void main() {
    int i = 1; int sum = 0;
    while (i<11) {
        sum = add(sum, i);
        i = add(i, 1);
    }
    printf("sum = %d\n", sum);
    printf("i = %d\n", i);
}
static int add(int a, int b)
{
    return(a+b);
}</pre>
```



An example program and its System Dependence Graph (SDG), both courtesy of GrammaTech Inc.

Fine granularity may not be necessary

Motivation

- Impact analysis
 - Mostly based on program <u>dependence analysis</u>
 - Commonly adopted at <u>method level</u> (even coarser levels)
- Program comprehension
 - Largely reduced to understanding program dependencies
 - More practical to explore <u>method-level</u> artifacts

Problems with fine-grained model

Motivation

Excessive overhead

Building the model is expensive or impractical

□ Low cost-effectiveness

Large overhead not well paid off

Problems with existing abstraction

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□ Static execute after (SEA) [J. Jasz et al., 2012]

ICFG (Interprocedural Control Flow Graph)



Background

Problems with existing abstraction

Background

□ Static execute after (SEA)

Further simplified as ICCFG (Interprocedural Component CFG)

- SEA := CALL U RET U SEQ
- SEA (A,B) => B depends on A

```
void main() {
    int i = 1; int sum = 0;
    while (i<11) {
        sum = add(sum, i);
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    printf("sum = %d\n", sum);
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}
static int add(int a, int b)
{
    return(a+b);
}</pre>
```



Approach

Solution

Method-level dependence abstraction

Model <u>complete</u> dependencies among methods <u>directly</u>

Goals

Improved precision

Compute dependencies explicitly

Improved cost-effectiveness

Trade precision for efficiency

Approach

METHOD DEPENDENCE GRAPH (MDG)

An abstraction of the SDG

Approach

□ The MDG abstraction

Ports

Statements at the boundary of a method

- Endpoints of interprocedural dependence edges
- Classification of ports
 - Incoming/outgoing ports (IP/OP)
 - Data-dependence (DD) / control-dependence (CD) ports



Approach

The MDG abstraction

- Interprocedural dependencies
 - Incoming/outgoing dependencies (ID/OD)
 - Data /control dependencies
 - Data dependencies: Parameter / Return / Heap
- Intraprocedural dependencies
 - Abstract with summary dependencies



An example MDG (top) and the closeup of one node M2 (bottom)

Approach

- Construction of MDG for a program P
 - Initialize MDG for P
 - For each method m in P
 - Find all CD ports on m
 - Find all DD ports on m
 - For each method m in P
 - Match OPs of m against IPs of all other methods
 - Build procedure dependence graph (PDG) of m [J. Ferrante et al., 1987]
 - Connect IPs to OPs in m based on the PDG of m

Approach

Data-Dependence (DD) port matching

DD type	Outgoing Port (OP)	Incoming Port (IP)
Parameter	Actual parameter at call site	Formal parameter at callee's entry
Return	Return value at callee	Use of return at caller site
Неар	Definition of heap variable	Use of heap variable

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Approach

Control-Dependence (CD) port matching

CD type	Outgoing Port (OP)	Incoming Port (IP)	
Normal	Branch / polymorphic call site	Entry of callee	
Exception-driven	Exception-throwing site	Entry of catch block that handles the exception	

Evaluating the MDG

Subject programs

Subject	KLOC	#Methods
Schedule1	0.3	24
NanoXml	3.5	282
Ant-v0	18.8	1,863
XML-security-v1	22.4	1,928
Jaba	37.9	3,332

Evaluating the MDG

Data

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- Method-level forward dependence sets
- Metrics
 - Effectiveness: precision and recall
 - Costs: time costs of MDG construction and querying
- □ Ground truth
 - Statement-level forward static slicing
 - Uplifted to method level slices

MDG is significantly more accurate

Evaluation

Results: precision



*Both techniques are sound (100% recall). The higher the bar, the better

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MDG remains efficient

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□ Results: costs

Abstraction time

Subject	SEA	MDG
Schedule 1	3s	4s
NanoXml	4s	9s
Ant-v0	1 <i>7</i> s	1 30s
XML-security-v1	22s	77s
Jaba	28s	302s
Overall average	14.8s	104.4s

MDG remains efficient

Results: costs

Mean querying time

Subject	SEA	MDG	Static slicing
Schedule 1	6ms	4ms	124ms
NanoXml	9ms	3ms	12,67ms
Ant-v0	64ms	45ms	34,896ms
XML-security-v1	50ms	43ms	24,092ms
JABA	213ms	121ms	444,188ms
Overall average	131.4ms	53.3ms	55737.9ms

Summing up

Contributions

- A new method-level program-dependence abstraction the method dependence graph (MDG)
- Empirical evidence showing the advantage of the MDG over the baseline abstraction approach (SEA)
- Study contrasting traditional dependence model and methodlevel abstraction for forward dependence analysis

□ Future work

- Improve hybrid dynamic analysis using the MDG
- Develop MDG-based program-comprehension tools

Acknowledgements

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Abstracting Program Dependencies using the Method Dependence Graph

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Problems with existing abstraction

- Component dependence graph [B. Li et al., 2005]
 - High-level <u>coarse</u> dependencies <u>among components</u> for component-based systems w/o traditional code-level analysis
- □ Influence graph [B. Breech et al., 2006]
 - Interface-level data dependencies among functions for procedural programs <u>w/o intraprocedural dependencies</u>
- Program summary graph [D. Callahan, 1988]
 - Interprocedural data dependencies <u>w/o control dependencies</u>
- □ Linkage grammar [S. Horwitz et al., 1990]
 - Statement-level dependencies (from in to out parameters)

MDG Construction Algorithm

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Algorithm 1 : BUILDMDG(program P, exception set unhandled)

- 1: G := empty graph // start with empty MDG of P
- 2: IP := OP := Ø // maps of methods to incoming/outgoing ports // Step 1: find ports
- 3: for each method m of P do
- 4: FINDDDPORTS(m, IP, OP)
- 5: FINDCDPORTS(m, IP, OP)
 - // Step 2: connect ports
- 6: for each method m of P do
- 7: for each DD port $z \in OP[m]$ do 8: add $\{\langle z, z' \rangle \mid \exists m' \text{ s.t. } z' \in IP$
 - add $\{\langle z, z' \rangle \mid \exists m' \text{ s.t. } z' \in IP[m'] \land data_dep(z,z')\}$ to G
- 9: COMPUTEINTERCDS(G, unhandled, m, IP, OP)
- 10: pdg := GETPDG(m)
- 11: for each port $z \in IP[m]$ do
- 12: add $\{\langle z, z' \rangle | z' \in OP[m] \land reaches(z, z', pdg)\}$ to node G_m
- 13: return G

Algorithm 2 : FINDDDPORTS(m, IP, OP)

- 1: for each call site cs in m do
- 2: for each callee m' of cs do
- 3: add $\{D(a, cs) \mid a \in actual_params(cs)\}$ to OP[m]
- 4: add $\{U(f, m') \mid f \in formal_params(m')\}$ to IP[m']
- 5: if return_type(m) \neq void then
- 6: add $\{D(rs) \mid rs \in return_sites(m)\}$ to OP[m]
- 7: for each caller site crs of m do
- 8: add $\{U(crs.s,rs) \mid rs \in return_sites(m)\}$ to IP[crs.m]
- 9: for each heap variable definition hd in m do add hd to OP[m]
- 10: for each heap variable use hu in m do add hu to IP[m]

Algorithm 3 : FINDCDPORTS(m, IP, OP)

- 1: add entry of m to IP[m] // entry represents all CD targets for callers
- 2: for each edge $\langle h, t \rangle$ in GETCDG(m) do
- 3: if t is a single-target call site then {add h to OP[m]}
- 4: if t unconditionally throws unhandled exception in m then
- 5: add h to OP[m]
- 6: for each multi-target call site cs in m do {add cs.s to OP[m]}
- 7: for each statement s in m do
- 8: If s catches interprocedural exception then {add s to IP[m]}
- 9: if s conditionally throws exception unhandled in m then
- 10: add s to OP[m]



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The *method dependence graph* offers a program abstraction of better cost-effectiveness tradeoff than both fine-grained model and existing alternative abstractions.